$$\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial r^{2}} + \frac{1}{r} \frac{\partial w}{\partial \theta} + w \frac{\partial w}{\partial z} = F_{3} - \frac{1}{\rho} \frac{\partial P}{\partial z}$$

$$+ v \left( \frac{\partial^{2} w}{\partial r^{2}} + \frac{1}{r} \frac{\partial w}{\partial \theta} + \frac{1}{r^{2}} \frac{\partial^{2} w}{\partial \theta^{2}} + \frac{\partial^{2} w}{\partial z^{2}} \right)$$
(14c)

where the nomenclature is

u, v, w . . . radial, circumferential, and longitudinal velocities, respectively, of fluid within bore of pressure pot, in/sec

F<sub>1</sub>,F<sub>2</sub>,F<sub>3</sub> . . . radial, circumferential, and longitudinal body forces per unit mass, respectively, acting on fluid in bore of pressure pot, lb/slug

If the condition of constant temperature is invoked, the coefficient of kinematic viscosity is a function of pressure only, that is

$$v = v(P) \tag{15}$$

From Figure 8, we see that the coordinate system is oriented such that there will be flow in the z-direction only, thus for axisymmetrical motion

$$u = v = \frac{\partial^2 w}{\partial \Theta^2} = 0 \tag{16}$$

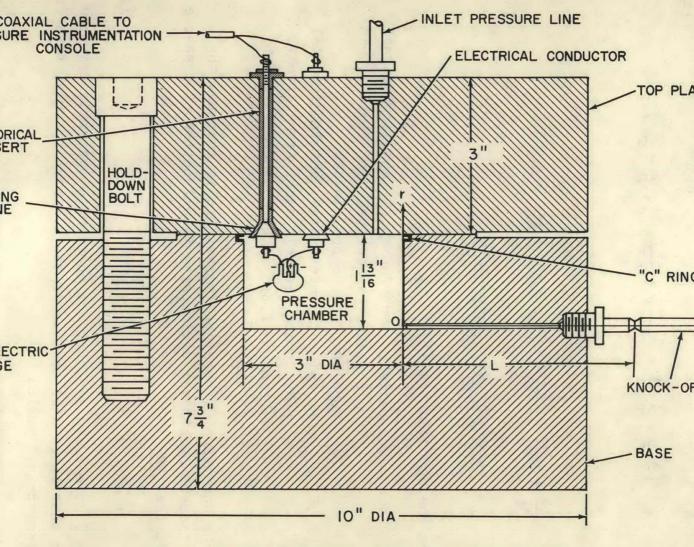


FIG. 8 CROSS-SECTIONAL VIEW OF PRESSURE POT